

IEEE ICNSC 2020

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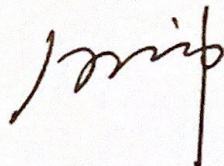
to the paper titled

Robot Navigation with Map-Based Deep Reinforcement Learning

by Guangda Chen, Lifan Pan, Yu'an Chen, Pei Xu, Zhiqiang Wang, Peichen Wu, Jianmin Ji and Xiaoping Chen.

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Xianzhong Zhou, Professor, Nanjing University,
General Chair of IEEE ICNSC 2020